DATE: Friday, October 13, 2006

<u>L1</u>

plurality adj sensor

Freeform Search

Database	US Pre-Grant Publication Full-Text Database US Patents Full-Text Database US OCR Full-Text Database EPO Abstracts Database JPO Abstracts Database Derwent World Patents Index IBM Technical Disclosure Bulletins			
Term:	117 and L18			
Display:	Documents in <u>Display Format</u> : Starting with Number 1			
Generate: C Hit List @ Hit Count C Side by Side C Image				
Search Clear Interrupt				

Search History

Printable Copy

Create Case

<u>L1</u>

27167

Set Name side by side	Query	Hit Count	Set Name result set
DB=PGPI	B, USPT, USOC, EPAB, JPAB, DWPI, TDBD; PLUR =	YES; OP=OR	
<u>L19</u>	117 and L18	. 34	<u>L19</u>
<u>L18</u>	grip or (coefficient adj friction)	593972	<u>L18</u>
<u>L17</u>	15 and L16	89	<u>L17</u>
<u>L16</u>	vehicle	2129867	<u>L16</u>
<u>L15</u>	vehicle	2129867	<u>L15</u>
<u>L14</u>	(load adj value) and (original adj value)	254	<u>L14</u>
<u>L13</u>	13 and L12	1	<u>L13</u>
<u>L12</u>	contact adj load adj value	15	<u>L12</u>
<u>L11</u>	15 and L10	0	<u>L11</u>
<u>L10</u>	ground adj sensor	1122	<u>L10</u>
<u>L9</u>	15 and L8	1	<u>L9</u>
<u>L8</u>	ground same (load adj sensor)	283	<u>L8</u>
<u>L7</u>	ground near (load adj sensor)	18	<u>L7</u>
<u>L6</u>	ground near4 (load adj sensor)	46	<u>L6</u>
<u>L5</u>	· 13 and L4	89	<u>L5</u>
<u>L4</u>	wheel adj sensor	5210	<u>L4</u>
<u>L3</u>	11 and L2	886	<u>L3</u>
<u>L2</u>	vehicle adj control\$	55599	<u>L2</u>

Purge Queries

END OF SEARCH HISTORY

Refine Search

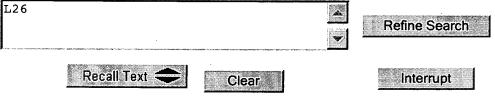
Search Results -

Terms	Documents
L17 and L25	0

Database:

US Pre-Grant Publication Full-Text Database US Patents Full-Text Database US OCR Full-Text Database EPO Abstracts Database JPO Abstracts Database Derwent World Patents Index IBM Technical Disclosure Bulletins

Search:



Search History

DATE: Friday, October 13, 2006 **Purge Queries** Printable Copy Create Case

Set Name Query side by side	Hit Count	Set Name result set
DB= $PGPB$, $USPT$, $USOC$, $EPAB$, $JPAB$, $DWPI$, $TDBD$; $PLUR$ = YES ; OP = OR		
<u>L26</u> 117 and L25	0	<u>L26</u>
<u>L25</u> 120 or 124	96	<u>L25</u>
DB=USPT; $PLUR=YES$; $OP=OR$		
(4106821 4409664 4430703 3752536 4420814 3503653 4499543 4113321 4 4657313 4267575 3930688 4497026 4136912 4494801 4392202 3880474 44 L24	108290 287505 38	L24
<u>L23</u> ("4736994" "4718013" "4674049" "4701854")[PN]	4	<u>L23</u>
(4106821 4409664 4430703 3752536 4420814 3503653 4499543 4113321 4 4657313 4267575 3930688 4497026 4136912 4494801 4392202 3880474 44 <u>L22</u> 4315213 4384330 2914359 4569560 3637264 4430714 4643492 4435768 42 3943345 4270176 4515412 4345796 4335431 3398995 4439832 3985396 43 4363523 3938612)![PN]	108290 287505 38	<u>L22</u>
<u>L21</u> ("4736994" "4718013" "4674049" "4701854")[PN]	4	<u>L21</u>
<u>L20</u> ("4718013" "4674049" "4701854")[URPN]	58	<u>L20</u>
DB = PGPB, USPT, USOC, EPAB, JPAB, DWPI, TDBD; PLUR = YES; OP = OR		
http://jupiter2:9000/bin/cgi-bin/PreSearch.pl	. 10)/13/06

WĖST	Refine Search	Page	2 of 2)
<u>L19</u>	117 and L18	34	<u>L19</u>	
<u>L18</u>	grip or (coefficient adj friction)	593972	<u>L18</u>	
<u>L17</u>	15 and L16	89	<u>L17</u>	
<u>L16</u>	vehicle	2129867	<u>L16</u>	
<u>L15</u>	vehicle	2129867	<u>L15</u>	
<u>L14</u>	(load adj value) and (original adj value)	254	<u>L14</u>	
<u>L13</u>	13 and L12	1	<u>L13</u>	
<u>L12</u>	contact adj load adj value	15	<u>L12</u>	
<u>L11</u>	15 and L10	0	<u>L11</u>	
<u>L10</u>	ground adj sensor	1122	<u>L10</u>	
<u>L9</u>	15 and L8	1	<u>L9</u>	
<u>L8</u>	ground same (load adj sensor)	283	<u>L8</u>	
<u>L7</u>	ground near (load adj sensor)	18	<u>L7</u>	
<u>L6</u>	ground near4 (load adj sensor)	46	<u>L6</u>	
<u>L5</u>	13 and L4	. 89	<u>L5</u>	
<u>L4</u>	wheel adj sensor	5210	<u>L4</u>	
<u>L3</u>	l1 and L2	886	<u>L3</u>	
<u>L2</u>	vehicle adj control\$	55599	<u>L2</u>	
<u>L1</u>	plurality adj sensor	27167	L1	

END OF SEARCH HISTORY